

# Symmetry Breaking in the Subgraph Isomorphism Problem

*WHOOPS Workshop 2024*

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# Graph Isomorphism

Graphs  $G$  and  $H$  are *isomorphic* if there exists a bijection between their vertex sets that preserves adjacency.

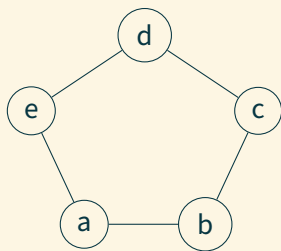


Figure: The graph  $G$ .

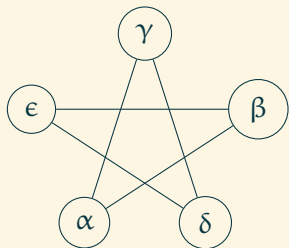


Figure: The (isomorphic) graph  $H$ .

# Subgraph Isomorphism Problem (SIP)

Given a pattern graph  $P$  and a (larger) target graph  $T$ , does there exist a graph isomorphism between  $P$  and a subgraph of  $T$ ?

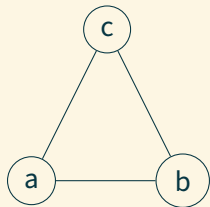


Figure: The pattern graph  $P$ .

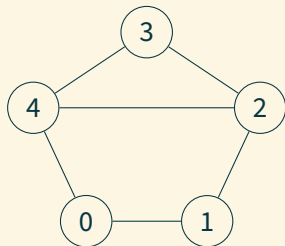


Figure: The target graph  $T$ .

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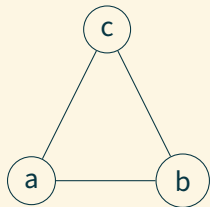


Figure: The pattern graph  $P$ .

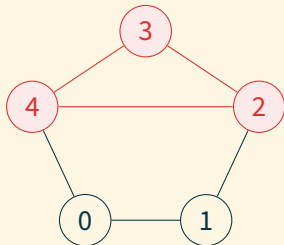


Figure: The target graph  $T$ .

# Subgraph Isomorphism Problem (SIP)

How many such solutions exist?

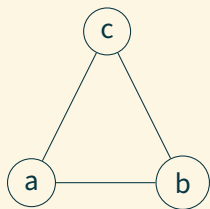


Figure: The pattern graph  $P$ .

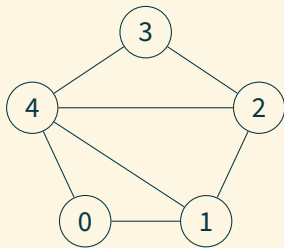


Figure: The target graph  $T$ .

# Subgraph Isomorphism Problem (SIP)

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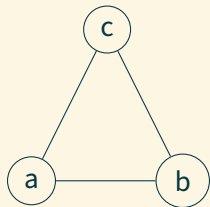
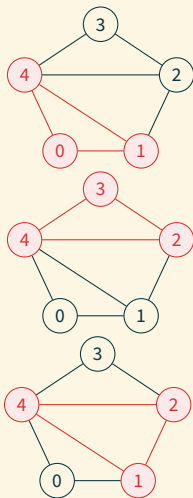
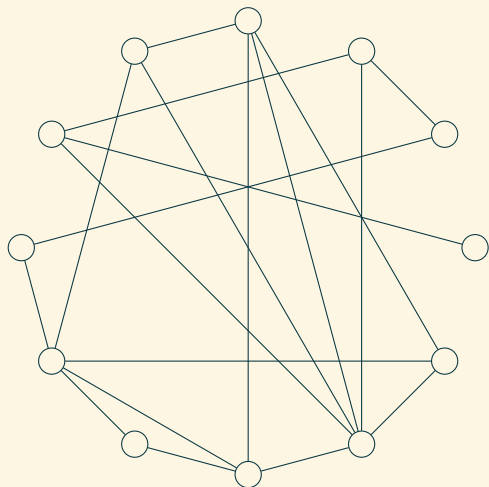


Figure: The pattern graph  $P$ .



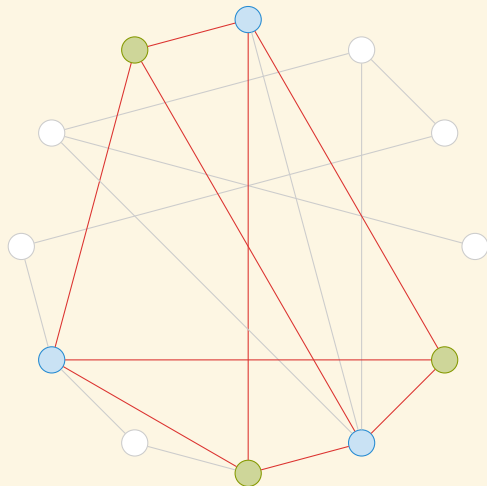
# A Larger Example

Is this graph planar?



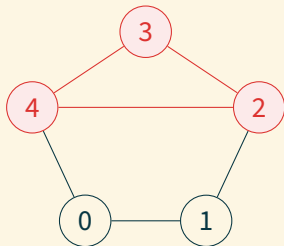
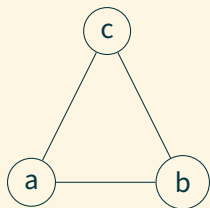
## A Larger Example

No! We've found  $K_{3,3}$  as a SIP solution, so  $G$  is non-planar (by Kuratowski's Theorem).





# Symmetry Breaking



## Solutions

$(a \rightarrow 2, b \rightarrow 3, c \rightarrow 4)$ ,  $(a \rightarrow 2, b \rightarrow 4, c \rightarrow 3)$ ,  
 $(a \rightarrow 3, b \rightarrow 2, c \rightarrow 4)$ ,  $(a \rightarrow 3, b \rightarrow 4, c \rightarrow 2)$ ,  
 $(a \rightarrow 4, b \rightarrow 2, c \rightarrow 3)$ ,  $(a \rightarrow 4, b \rightarrow 3, c \rightarrow 2)$

How do we avoid wasting time finding *symmetrical* solutions?

# Pattern Symmetries

An isomorphism of a graph onto itself is called an *automorphism*.

## **Lemma**

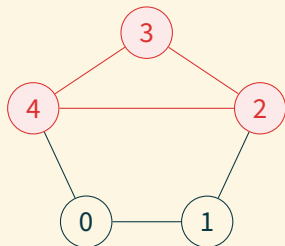
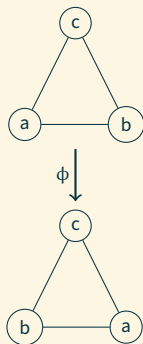
If an automorphism maps pattern vertex  $p_1 \rightarrow p_2$ , and a solution exists that maps  $p_1$  to target vertex  $t$ , then an equivalent solution exists for  $p_2 \rightarrow t$ .

The set of all vertices  $\{p_1, \dots, p_j\}$  such that  $p$  maps to all  $p_i$  under automorphism is called the *orbit* of  $p$ , denoted  $orb(p)$ .

# Pattern Symmetries

## Example

$\phi(a) = b$ , Solution 1 =  $(a \rightarrow 2, b \rightarrow 3, c \rightarrow 4) \implies \exists$  Solution 2 =  $(b \rightarrow 2, \dots)$

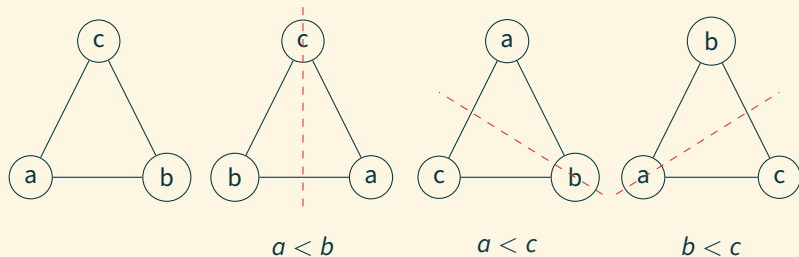


## Solution 2

$(b \rightarrow 2, a \rightarrow 3, c \rightarrow 4)$

# Pattern Symmetries

Consider the symmetries of the pattern graph, and the constraints we generate from them:



# Pattern Constraints

## Question

What does the pattern constraint  $a < b$  mean?

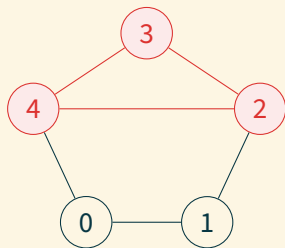
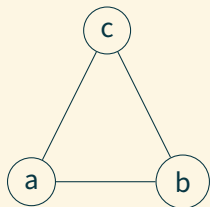
## Answer

*“The value assigned to variable  $a$  must be less\* than the value assigned to variable  $b$ .”*

\*More on this later...

# Pattern Symmetries

Now using the variable constraints  $a < b, a < c, b < c$ :



## Solutions

$(a \rightarrow 2, b \rightarrow 3, c \rightarrow 4), (a \rightarrow 2, b \rightarrow 4, c \rightarrow 3),$   
 $(a \rightarrow 3, b \rightarrow 2, c \rightarrow 4), (a \rightarrow 3, b \rightarrow 4, c \rightarrow 2),$   
 $(a \rightarrow 4, b \rightarrow 2, c \rightarrow 3), (a \rightarrow 4, b \rightarrow 3, c \rightarrow 2)$

# Target Symmetries

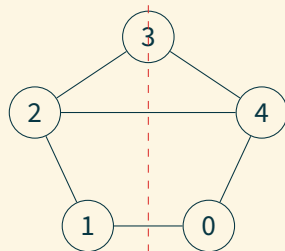
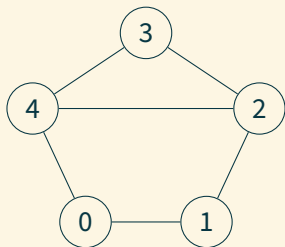
Similarly to pattern symmetries:

***Lemma***

If there exists an automorphism which maps target vertex  $t_1 \rightarrow t_2$ , and a solution mapping  $p \rightarrow t_1$ , an equivalent solution exists mapping  $p \rightarrow t_2$ .

# Target Symmetries

Consider the symmetries of the target:



$0 < 1$  or  $2 < 4$



# Pattern Constraints

## Question

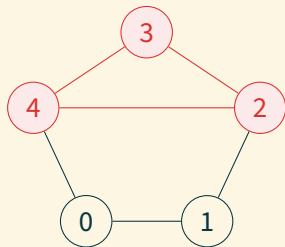
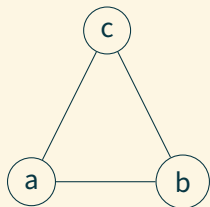
What does the target constraint  $5 < 3$  mean?

## Answer

*“The value 5 must be assigned to a smaller variable than the value 3, if the value 3 is assigned to a variable.”*

# Target Symmetries

Now using the value constraints  $2 < 4$ :



## Solutions

$(a \rightarrow 2, b \rightarrow 3, c \rightarrow 4)(a \rightarrow 2, b \rightarrow 4, c \rightarrow 3),$   
 $(a \rightarrow 3, b \rightarrow 2, c \rightarrow 4), (a \rightarrow 3, b \rightarrow 4, c \rightarrow 2),$   
 $(a \rightarrow 4, b \rightarrow 2, c \rightarrow 3), (a \rightarrow 4, b \rightarrow 3, c \rightarrow 2)$

# Target Symmetries

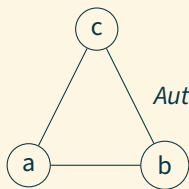
**Note:** Subgraph isomorphism is *non-surjective* on the target graph, so target constraints picked at random at the top of search may be ignored.

If we had picked  $0 < 1$  instead of  $2 < 4$ , we wouldn't have filtered any solutions.

# Generating Symmetry Constraints

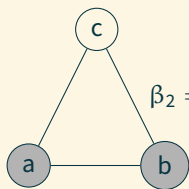
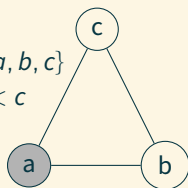
1. Compute generators for  $Aut(G)$ , the permutation group consisting of all automorphisms of the graph  $G$ .
2. For each generator  $g$ :
  - a. Pick a base point  $\beta$  to stabilise, recording its orbit.
  - b. Check which points still permute under  $g$  without moving  $\beta$ .
  - c. Repeat steps *a* and *b* with one such point, if one exists.
3. For all non-trivial base points  $\beta_1, \dots, \beta_n$ , add symmetry constraints  $\beta_i < \gamma \forall \gamma \in orb(\beta_i)$ .

# Example



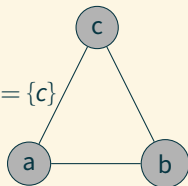
$$\text{Aut}(G) = \langle (abc), (ab) \rangle$$

$$\beta_1 = a, \text{orb}(a) = \{a, b, c\} \\ \implies a < b, a < c$$



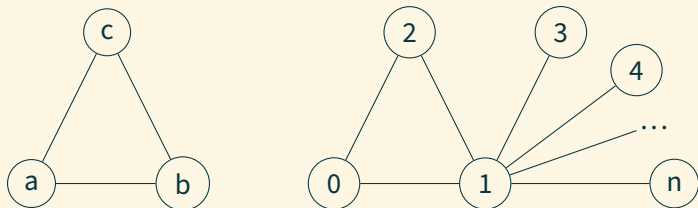
$$\beta_2 = b, \text{orb}(b)|_{\beta_1=a} = \{b, c\} \\ \implies b < c$$

$$\text{orb}(c)|_{\beta_1=a \wedge \beta_2=b} = \{c\}$$



# Flexible Ordering

**Generating constraints before search may waste effort.**



Using the fixed-order constraints generated at the top of search, we might propagate a list of constraints  $\{3 < n, 4 < n, \dots, n - 1 < n\}$  after each assignment that is never relevant to search.

## *How do we combat this?*

Fixed-order symmetry breaking picks a base at random before search. It could be unlucky, and pick one not relevant to the solution.

***We can construct the base during search, adding constraints as we go.*** When we encounter a vertex not already in the base, we add it to the base. The "smallest" element in each orbit is simply the element we encounter first in the search tree.

# Flexible Ordering

Suppose we have variable constraint  $a < b$  and value constraint  $4 < 2$ , and find a solution with  $(a \rightarrow 4, b \rightarrow 2, \dots)$ .

***We want to accept this solution.***

By constructing a *flexible value ordering* from the value constraints (such as  $[1, 2, 3, 4, 5, \dots] \rightarrow [1, 4, 2, 3, 5, \dots]$  in this case), we can avoid accidentally adding conflicting variable-value constraint pairs.



# Experimental Set-up

Experiments are run on the *Benchmarks for the Subgraph Isomorphism Problem* dataset found at

<https://perso.liris.cnrs.fr/christine.solnon/SIP.html>

Solver output is recorded, including: solution count, run-time, number of search nodes, and number of propagations.

# Initial Results (Variable and Value Symmetry Breaking)

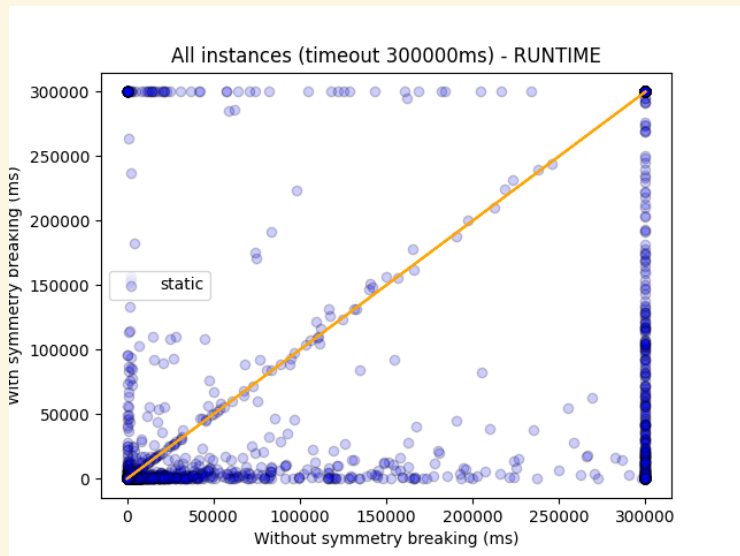


Figure: Fixed order symmetry breaking vs. No symmetry breaking

# Initial Results (Variable and Value Symmetry Breaking)

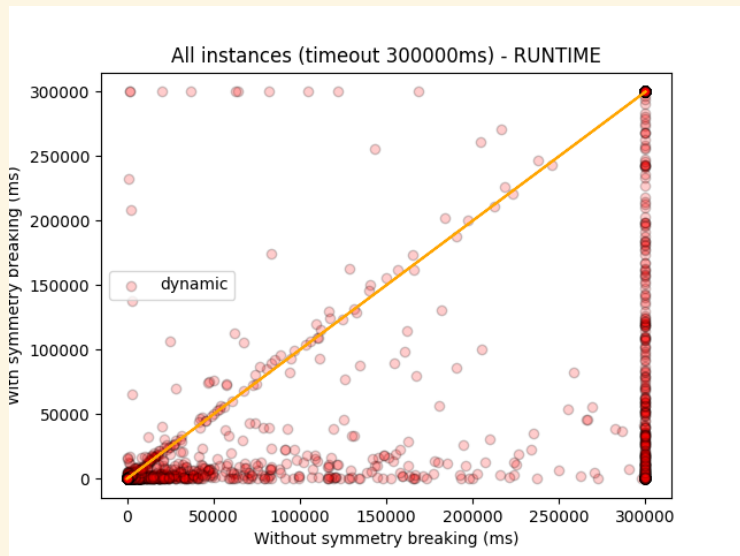


Figure: Flexible order symmetry breaking vs. No symmetry breaking

# Initial Results (Variable and Value Symmetry Breaking)

## *Number of previously timed-out cases now solved, and vice versa*

<i>Of 17006 instances:</i>	<b>Fixed Ordering</b>	<b>Flexible Ordering</b>
Now solved	178	213
Now timed-out	94	10

## *Average run-time relative to the solver with no symmetry breaking*

<b>Threshold (ms)</b>	<b>Fixed Ordering</b>	<b>Flexible Ordering</b>
100	12.79	1.46
500	3.21	1.25
1000	2.00	1.10
5000	1.10	0.83
10000	1.07	0.84
50000	0.89	0.85

# Initial Results (Variable and Value Symmetry Breaking)

## *Average relative run-time (unsatisfiable cases)*

<b>Threshold (ms)</b>	<b>Fixed Ordering</b>	<b>Flexible Ordering</b>
100	22.37	1.96
500	18.10	4.25
1000	11.97	3.78
5000	3.93	1.03
10000	3.79	1.08
50000	1.35	0.87

## *Average relative run-time (satisfiable cases)*

<b>Threshold (ms)</b>	<b>Fixed Ordering</b>	<b>Flexible Ordering</b>
100	0.53	0.57
500	0.47	0.33
1000	0.46	0.32
5000	0.46	0.26
10000	0.43	0.24
50000	0.34	0.20

Any questions?