

Proof Logging for Pseudo-Boolean Optimization

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WHOOPS '25, Orsay, France
September 13, 2025

*Based on joint work with Daniel Le Berre, Magnus O. Myreen,
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 - ▶ **Trustworthiness**:
 - ★ Proofs are fully complete, so each step easy to check
 - ★ Checker has a formally verified backend

Proof Logging: Existing Work Beyond SAT

- Constraint Programming:
 - ▶ Early work [VS10]: no full coverage, not trustworthy
 - ▶ *VeriPB* Proof Logging [EGMN20, GMN22, MM23, MMN24, MM25]: efficiency is a problem (e.g. logging overhead $\times 10$, checking overhead $\times 1000$)

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- SMT solving: *Alethe* [SFBF21], *Carcara* [ALB23]: no full coverage, efficiency problem

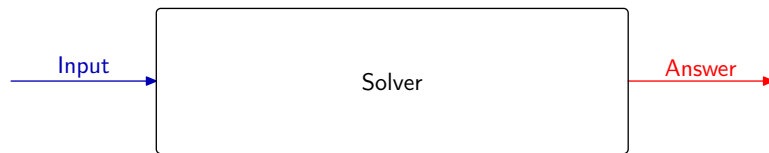
This Talk

- Efficient *VeriPB* proof logging and checking for pseudo-Boolean optimization [KLM⁺25]
- Covers all techniques in state-of-the-art solvers *RoundingSat* [EN18] and *Sat4j* [LP10]

This Talk

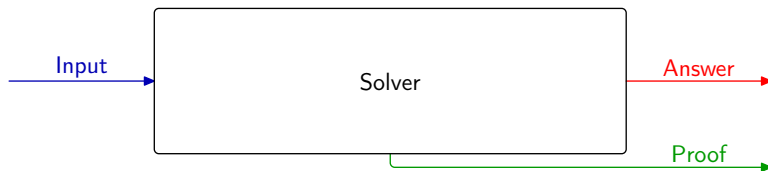
- Efficient *VeriPB* proof logging and checking for pseudo-Boolean optimization [KLM⁺25]
- Covers all techniques in state-of-the-art solvers *RoundingSat* [EN18] and *Sat4j* [LP10]
- Performance close to our goals:
 - ▶ Proof logging overhead usually $\leq 10\%$ (worst-case 50%)
 - ▶ Checking overhead usually $\leq \times 6$ (worst-case $\times 20$)
- First time practically feasible proof logging beyond SAT

Proof Logging with Certifying Solvers: Workflow



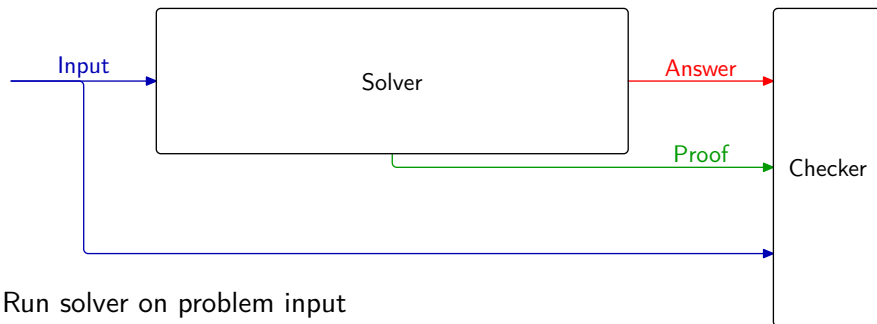
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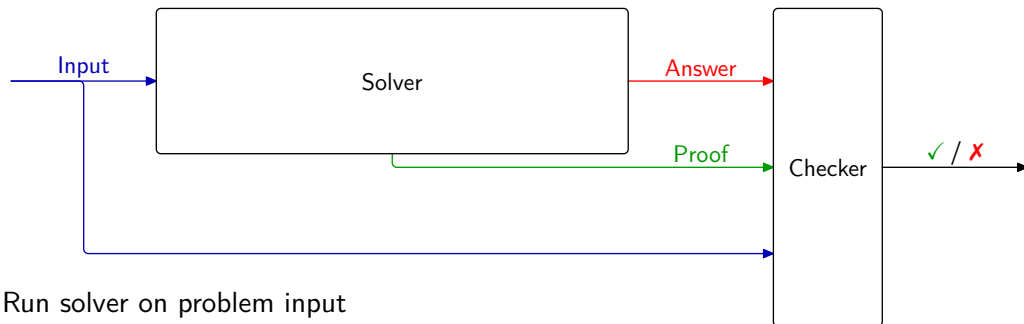
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- ① Run solver on problem input
- ② Get as output not only answer but also proof
- ③ Feed input + answer + proof to proof checker
- ④ Verify that proof checker says answer is correct

Overview of This Talk

- 1 Pseudo-Boolean Solving and Optimization
- 2 The *VeriPB* Proof System
- 3 Optimization Techniques
- 4 Core-Guided Optimization
- 5 LP Integration
- 6 Empirical Results
- 7 Concluding Remarks

Pseudo-Boolean Optimization

- Operates on 0-1 integer linear inequalities or pseudo-Boolean constraints:

$$\sum_i a_i \ell_i \geq A$$

- ▶ $a_i, A \in \mathbb{Z}$
- ▶ **literals** ℓ_i : x_i or \bar{x}_i (where $x_i + \bar{x}_i = 1$)
- ▶ variables x_i take values 0 (false) or 1 (true)

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 - Clauses: $x_1 \vee x_2 \vee \bar{x}_3 \iff x_1 + x_2 + \bar{x}_3 \geq 1$

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 - General constraints: $3x_1 + 2x_2 + x_3 + x_4 \geq 3$

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- **Propagation**: Infer literal values from single constraint and other literal values
Example: After deciding $x_1 = 0$, constraint $3x_1 + 2x_2 + x_3 + x_4 \geq 3$ propagates $x_2 = 1$
- **Conflict-driven search**:
 - ▶ Try to build satisfying assignment literal by literal using decisions and propagations
 - ▶ When falsifying constraint, derive constraint explaining the conflict and add to formula

Conflict Analysis Example

- Let

$$C_1 \doteq \bar{z} + \bar{w} \geq 1$$

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Approaches for Pseudo-Boolean Solving and Optimization

- Two main approaches for pseudo-Boolean solving:
 - ▶ CNF-based: Translate to CNF and run conflict-driven clause learning (CDCL)
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 - ▶ Native PB: Generalize conflict-driven search to pseudo-Boolean constraints ([focus of this talk](#))
- New challenges and techniques for native PB solving compared to SAT:
 - ▶ Efficient propagation [Dev20, NORZ24]
 - ▶ Linear programming (LP) integration [DGN21]
 - ▶ Optimization techniques, e.g. solution-improving search, core-guided search [DGD⁺21]

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 - ▶ In PB, explicit description of conflict analysis steps required
- Other techniques pose further challenges:
 - ▶ Objective rewriting in core-guided search
 - ▶ Linear programming (LP) integration (Farkas certificates, cut generation, ...)
- Low-level challenges for truly efficient proof logging and checking:
 - ▶ Logging unit constraints (saying that a variable must take some fixed value, e.g. $x_2 \geq 1$)
 - ▶ Logging constraint simplifications (e.g. simplifying away variables with fixed values)
 - ▶ Logging and checking solutions
 - ▶ Optimizing formally verified proof checking

Pseudo-Boolean Proof Logging Basics

Pseudo-Boolean proof logging based on cutting planes proof system [CCT87]

Input axioms

From the input

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Addition

$$\frac{\sum_i a_i \ell_i \geq A \quad \sum_i b_i \ell_i \geq B}{\sum_i (a_i + b_i) \ell_i \geq A + B}$$

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Division for any $c \in \mathbb{N}^+$

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The Division Rule

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Proof of soundness:

- Dividing $\sum_i a_i \ell_i \geq A$ by c yields $\sum_i \frac{a_i}{c} \ell_i \geq \frac{A}{c}$

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Division is crucial for Boolean (as opposed to real-valued) reasoning:

- Addition and multiplication valid over the reals
- Literal axioms $\ell_i \geq 0$ and $\overline{\ell_i} = 1 - \ell_i \geq 0$ valid for all reals in $[0, 1]$
- Division only valid over the integers: e.g. $2x_1 \geq 1$ implies $x_1 \geq 1$

Conflict Analysis Example: *VeriPB* Derivation

$$\begin{array}{rcl}
 \text{Add} & \frac{\bar{z} + \bar{w} \geq 1 \quad \bar{y} + w \geq 1}{\bar{y} + \bar{z} \geq 1} & \\
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such a calculation is written in the proof log in reverse Polish notation as

pol @C1 @C2 + @C3 + 2 d ;

Advanced Pseudo-Boolean Proof Logging

We need a rule for deriving non-implied constraints (e.g. introducing new variables)

Redundance-based strengthening ([BT19, GN21], inspired by [JHB12], simplified)

F and $F \cup \{C\}$ are **equisatisfiable** if there is a **substitution** ω (mapping variables to truth values or literals), called a **witness**, for which

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When using rule in a proof, the implication needs to be **efficiently verifiable** — every $D \in (F \cup \{C\})|_{\omega}$ should follow from $F \cup \{\neg C\}$ either “obviously” or by explicit derivation

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$\neg C_2 \doteq x_1 + x_2 + x_3 \leq 1 + y_3$ implies $C_1 \upharpoonright_\omega \doteq x_1 + x_2 + x_3 \leq 2$

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VeriPB:

```

red +1 x1 +1 x2 +1 x3 -1 y3 <= 2 : y3 -> 1;
red +1 x1 +1 x2 +1 x3 -1 y3 >= 2 : y3 -> 0;
```

Proof by Contradiction

- F and $F \cup \{C\}$ are equisatisfiable if $F \cup \{\neg C\} \models \perp$
- Can be seen as a special case of the redundance rule (empty witness ω)

Proof by Contradiction: Example

- From

$$C_1 \doteq 2t + x_1 + x_2 \geq 2 \quad C_2 \doteq 2\bar{t} + x_1 + x_2 \geq 2$$

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pbcc +1 x1 +1 x2 >= 2 : subproof

VeriPB: pol @C1 -1 + 2 d @C2 -1 + 2 d + ;
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 - ▶ Satisfiable instances: just provide a solution
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 - ▶ Satisfiable instances: just provide a solution
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- Optimization problems: provide:
 - (i) a solution with value UB , and
 - (ii) a derivation of the inequality $Obj \geq LB$

(Optimality proven if $UB = LB$)

Optimization Techniques: Solution-Improving Search

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 - ▶ Final contradiction implies $Obj \geq v^*$
- Example: Let $Obj = x_1 + 2x_2 + x_3$
 We find the solution $x_1 = x_3 = 1, x_2 = 0$ with objective value 2
 Then `sol1 x1 ~x2 x3` introduces constraint $Obj \leq 1$, i.e. $x_1 + 2x_2 + x_3 \leq 1$

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- Can also do this starting from pre-chosen literal values
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- These pre-chosen values are called **assumptions**
- Possible outcomes:
 - ▶ Consistent \rightarrow find solution to formula
 - ▶ Inconsistent \rightarrow learn constraint (called **core**) why assumptions are inconsistent

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 $\neg C_2 \doteq x_2 + x_3 + x_4 \leq 1 + y_3$ implies $C_1 \upharpoonright_\omega \doteq x_2 + x_3 + x_4 \leq 2$

Proof Logging for Core-Guided Optimization: Example

We know $D \doteq x_2 + x_3 + x_4 \geq 2$. Want to introduce a variable y_3 such that

$$x_2 + x_3 + x_4 = 2 + y_3, \quad \text{i.e.} \quad \begin{cases} C_1 & \doteq x_2 + x_3 + x_4 \leq 2 + y_3 \\ C_2 & \doteq x_2 + x_3 + x_4 \geq 2 + y_3 \end{cases}$$

using condition $F \cup \{\neg C\} \models (F \cup \{C\})|_\omega$.

- $F \cup \{\neg C_1\} \models (F \cup \{C_1\})|_\omega$

Choose $\omega = \{y_3 \mapsto 1\}$ — F untouched; new constraint $C_1|_\omega$ trivially satisfied

- $F \cup \{C_1\} \cup \{\neg C_2\} \models (F \cup \{C_1\} \cup \{C_2\})|_\omega$

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VeriPB:

```

red +1 x2 +1 x3 +1 x4 -1 y3 <= 2 : y3 -> 1;
red +1 x2 +1 x3 +1 x4 -1 y3 >= 2 : y3 -> 0;
```

Proof Logging for Core-Guided Optimization: Some Further Details

$$Obj_{\text{orig}} = x_1 + 2(x_2 + x_3 + x_4) + x_3 + 2x_4$$

$$Obj_{\text{rewritten}} = x_1 + 2(2 + y_3) + x_3 + 2x_4$$

- Multiplying $x_2 + x_3 + x_4 \geq 2 + y_3$ by 2 yields inequality $Obj_{\text{orig}} \geq Obj_{\text{rewritten}}$ (after canceling rest of objective from both sides)
- Used to show, e.g., that $Obj_{\text{rewritten}} \geq LB$ implies $Obj_{\text{orig}} \geq LB$
- Other inequality needed in solver

LP Relaxation

- Linear programming (LP) relaxation: allow variables to take any real value in $[0, 1]$
- In practice usually solved quickly using simplex algorithm
- Relaxation has a better/lower optimal objective value

Pseudo-Boolean Solving: LP Integration

- Recall: conflict-driven search tries to build satisfying assignment
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- Recall: conflict-driven search tries to build satisfying assignment
- Partial assignments may yield unsatisfiable subproblem even over the reals
- Propagation does not necessarily detect this, but LP solving can
- Possible outcomes when solving LP relaxation on formula + partial assignment:
 - ▶ infeasibility → generate **Farkas certificate**
 - ▶ found integral solution → this solution is optimal
 - ▶ found fractional solution → add constraints ‘cutting away’ fractional solution: **cut generation**

Farkas Certificates

If solver decides $y = 0$, then constraints

$$C_1 \doteq y + x_1 + x_2 + x_3 \geq 2$$

$$C_2 \doteq y + 3x_1 + 2x_2 + x_3 + x_4 \geq 3$$

$$C_3 \doteq -2x_1 - 2x_2 - x_3 \geq -1$$

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Round multipliers provided by LP solver to integers and check in exact arithmetic

Farkas Certificates: Proof Logging

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a Farkas certificate is

$$C_1 + C_2 + 2 \cdot C_3 + (\overline{x_4} \geq 0) + (x_2 \geq 0) \doteq 2y \geq 2$$

Divide by 2 to get $y \geq 1$

Farkas Certificates: Proof Logging

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VeriPB: `pol @C1 @C2 + @C3 2 * + ~x4 + x2 + 2 d;`

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- ▶ Cutting planes division by 2 yields $x_1 + x_2 + x_3 \geq 2$
- ▶ *VeriPB*: `pol @C1 @C2 + @C3 + 2 d;`

Advanced Cut Generation

- Cut generation with **mixed integer rounding (MIR)** rule [MW01, DGN21] more challenging
- MIR rule is stronger than cutting planes division
- Reasoning uses integer slack variables (not supported by *VeriPB*)
- Proof logging instead uses **proof by contradiction**

Advanced Cut Generation: MIR cut

- MIR cut: given a constraint $\sum_i a_i \ell_i \geq A$ and a divisor $d \in \mathbb{N}^+$, derive

$$\sum_i \left(\min \{a_i \bmod d, A \bmod d\} + \left\lfloor \frac{a_i}{d} \right\rfloor (A \bmod d) \right) \ell_i \geq \left\lceil \frac{A}{d} \right\rceil (A \bmod d)$$

- We call $R = A \bmod d$ the multiplier of the MIR cut
- Example: Applying a MIR cut with divisor $d = 5$ to

$$10x_1 + 5x_2 + 6x_3 + 3x_4 + x_5 \geq 12$$

yields

$$4x_1 + 2x_2 + 3x_3 + 2x_4 + x_5 \geq 6$$

- Cutting planes division by $d = 5$ and multiplying by $R = 12 \bmod 5 = 2$ yields weaker constraint

$$4x_1 + 2x_2 + 4x_3 + 2x_4 + 2x_5 \geq 6$$

Advanced Cut Generation: Example

- For constraints

$$C_1 \doteq 6x_1 + 5x_2 + 2x_3 + 3x_4 \geq 8, \quad C_2 \doteq x_1 + x_3 \geq 1$$

introduce integral slack variables $s_1, s_2 \geq 0$ to obtain

$$C'_1 \doteq 6x_1 + 5x_2 + 2x_3 + 3x_4 - s_1 = 8, \quad C'_2 \doteq x_1 + x_3 - s_2 = 1$$

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- Compute linear combination $C'_1 + 4 \cdot C'_2$, and only keep \geq part:

$$10x_1 + 5x_2 + 6x_3 + 3x_4 - s_1 - 4s_2 \geq 12$$

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- Apply a MIR cut with divisor $d = 5$ (multiplier $R = 12 \bmod 5 = 2$):

$$4x_1 + 2x_2 + 3x_3 + 2x_4 - s_2 \geq 6$$

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$$4x_1 + 2x_2 + 3x_3 + 2x_4 - s_2 \geq 6$$

- Subtract C'_2 to obtain

$$3x_1 + 2x_2 + 2x_3 + 2x_4 \geq 5$$

Proof Logging for Advanced Cut Generation: Example

$$C_1 \doteq 6x_1 + 5x_2 + 2x_3 + 3x_4 \geq 8, \quad C_2 \doteq x_1 + x_3 \geq 1$$

- We prove resulting cut $D \doteq 3x_1 + 2x_2 + 2x_3 + 2x_4 \geq 5$ by contradiction
- Can use negation $\neg D \doteq 3x_1 + 2x_2 + 2x_3 + 2x_4 \leq 4 \doteq -3x_1 - 2x_2 - 2x_3 - 2x_4 \geq -4$

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$$-3x_1 - 2x_2 - 2x_3 - 2x_4 \geq -4 \quad 6x_1 + 5x_2 + 2x_3 + 3x_4 \geq 8$$

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$$\text{Add } \frac{-3x_1 - 2x_2 - 2x_3 - 2x_4 \geq -4 \quad 6x_1 + 5x_2 + 2x_3 + 3x_4 \geq 8}{3x_1 + 3x_2 + x_4 \geq 4}$$

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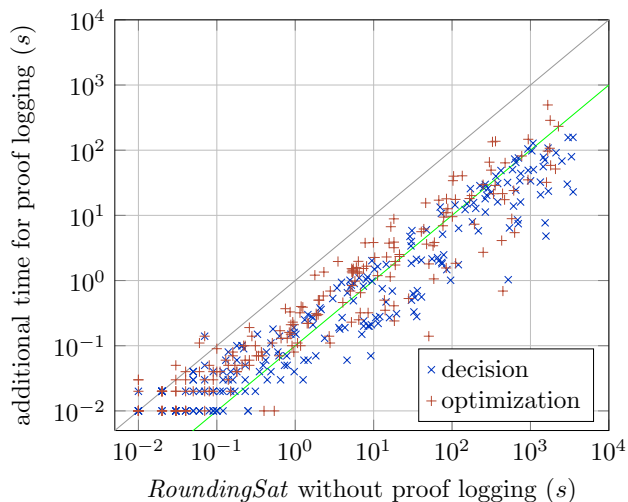
pbcc +3 x1 +2 x2 +2 x3 +2 x4 >= 5 : subproof

VeriPB: pol -1 @C1 + 3 d 2 * -1 + @C2 + ;

qed pbcc : -1;

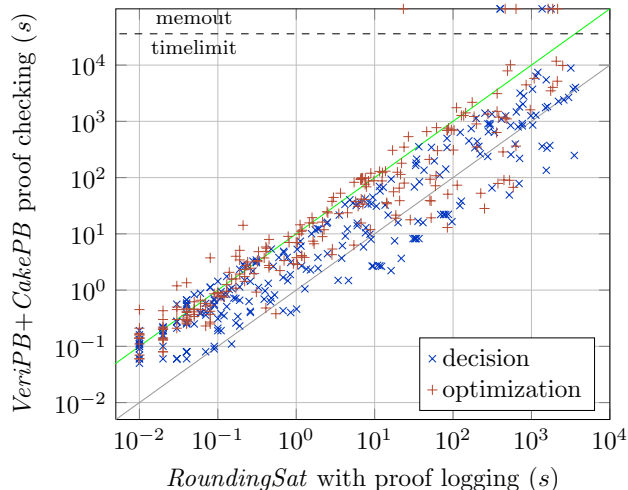
Empirical Results: Proof Logging Overhead for *RoundingSat*

- Usually $\leq 10\%$
- Decision instances: worst-case 20%
- Optimization instances: worst-case 50%
- Goal: $\leq 10\%$
- Overheads gets smaller for larger solving times



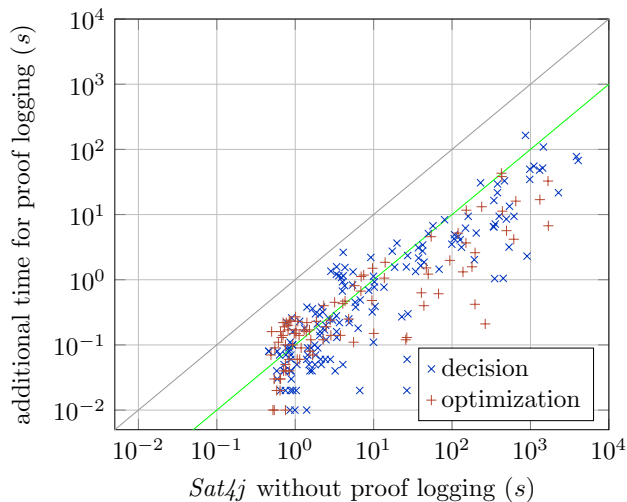
Empirical Results: Proof Checking Overhead for *RoundingSat*

- Usually $\leq \times 6$
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worst-case $\times 10$
- Optimization instances:
worst-case $\times 20$
- Goal: $\leq \times 10$



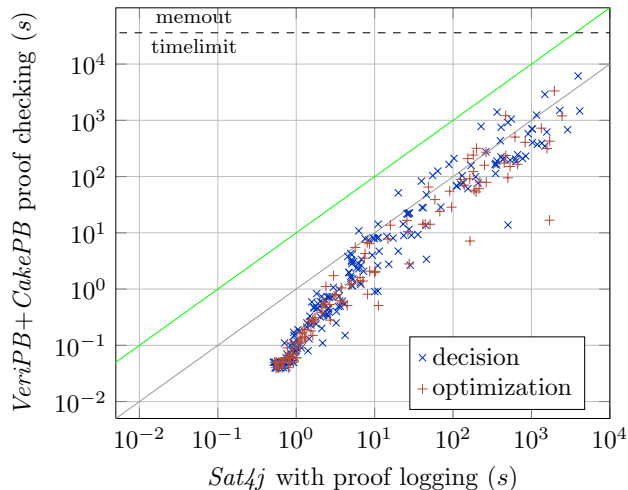
Empirical Results: Proof Logging Overhead for *Sat4j*

- Usually $\leq 10\%$
- Worst-case 60%
- Goal: $\leq 10\%$



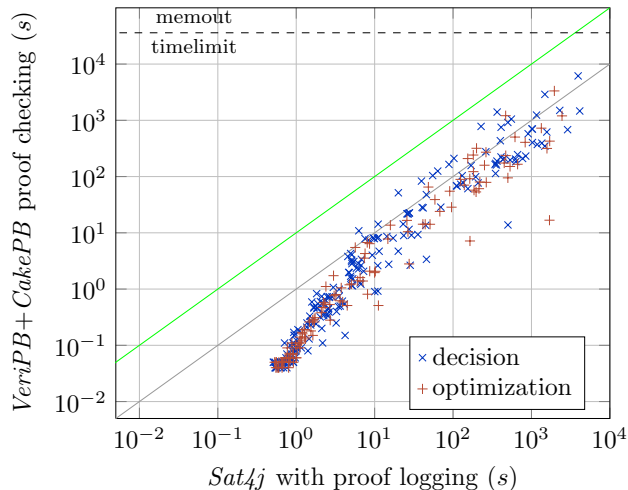
Empirical Results: Proof Checking Overhead for *Sat4j*

- Usually $\leq \times 2$
- Worst-case $\times 4$
- Goal: $\leq \times 10$



Empirical Results: Proof Checking Overhead for *Sat4j*

- Usually $\leq \times 2$
- Worst-case $\times 4$
- Goal: $\leq \times 10$
- Lower overheads than *RoundingSat*:
 - ▶ Fewer advanced techniques
 - ▶ Java is a bit slower than C++



Using Proof Logging to Detect Inefficiency Bugs

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- Two examples:
 - ▶ Unnecessarily large coefficient in a constraint
 - ▶ Solver used $Obj \leq v$ instead of objective-improving constraint $Obj \leq v - 1$
- Having to specify derivation explicitly (in contrast to SAT) can also be an advantage

Challenges for Efficient Proof Logging and Checking

- Attention to detail
 - ▶ Caveat: many low-level details skipped
 - ▶ Getting these right requires in-depth understanding of both solver and *VeriPB*
 - ▶ So efficient proof logging is not just adding a few simple print statements

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 - ▶ Getting these right requires in-depth understanding of both solver and *VeriPB*
 - ▶ So efficient proof logging is not just adding a few simple print statements
- Different perspectives in solver and proof checker
 - ▶ *Sat4j* simplifies input constraints but considers them “the same”
 - ▶ In the proof these constraints are clearly different
 - ▶ Requires painful book-keeping during proof logging
 - ▶ New feature of labelling constraints very helpful for this

Future Work

- Even faster proof logging and checking for pseudo-Boolean optimization
 - ▶ Branch-and-bound search (checking solutions currently a bottleneck)
 - ▶ Native efficient support for simplifications of constraints
 - ▶ Low-level optimizations in *VeriPB* and formally verified backend *CakePB*

Future Work

- Even faster proof logging and checking for pseudo-Boolean optimization
 - ▶ Branch-and-bound search (checking solutions currently a bottleneck)
 - ▶ Native efficient support for simplifications of constraints
 - ▶ Low-level optimizations in *VeriPB* and formally verified backend *CakePB*
- Faster proof logging and checking for further paradigms:
 - ▶ MaxSAT solving
 - ▶ Subgraph solving
 - ▶ Constraint programming
 - ▶ ...

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Thank you! Any questions?

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